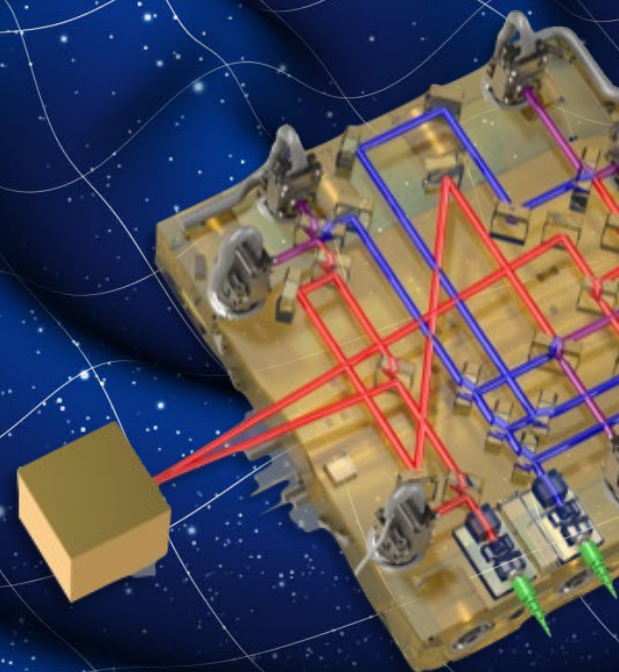




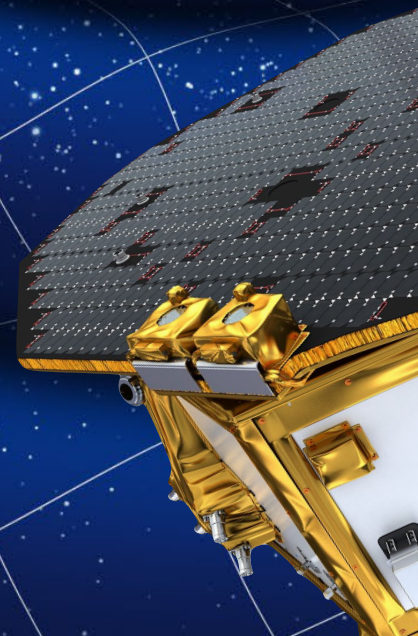
**lisa pathfinder**

# Short history of the LPF interferometer

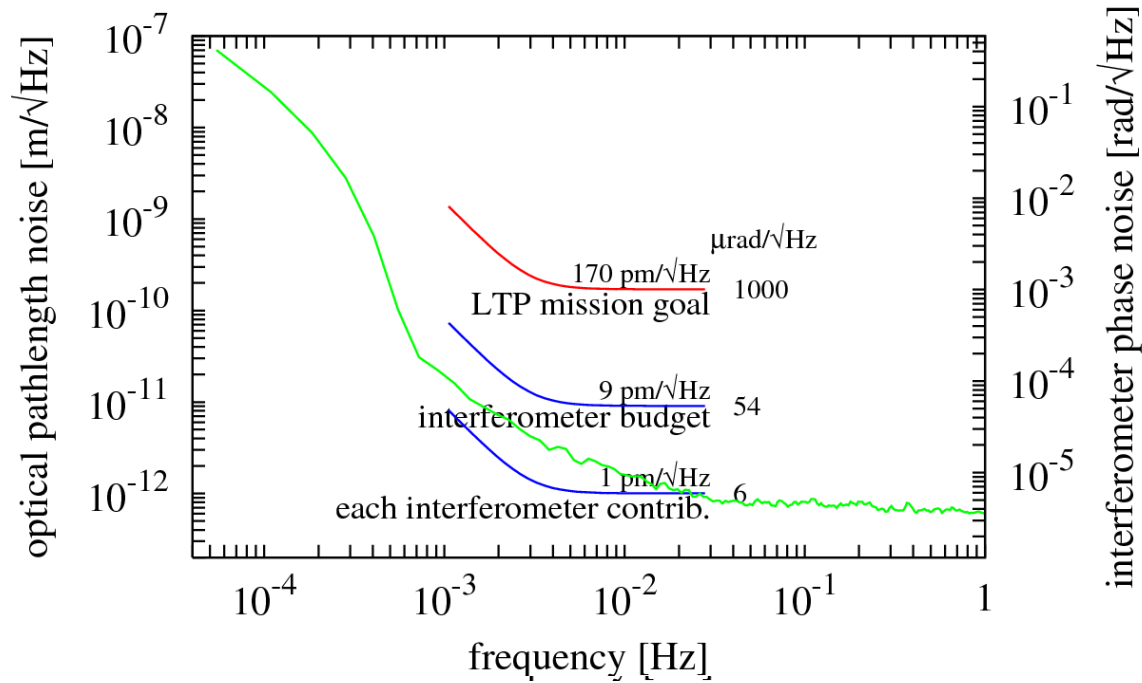


Gerhard Heinzel,  
AEI Hannover,  
10<sup>th</sup> anniversary, Barcelona, 12/2025

Disclaimer: Personal, biased and incomplete



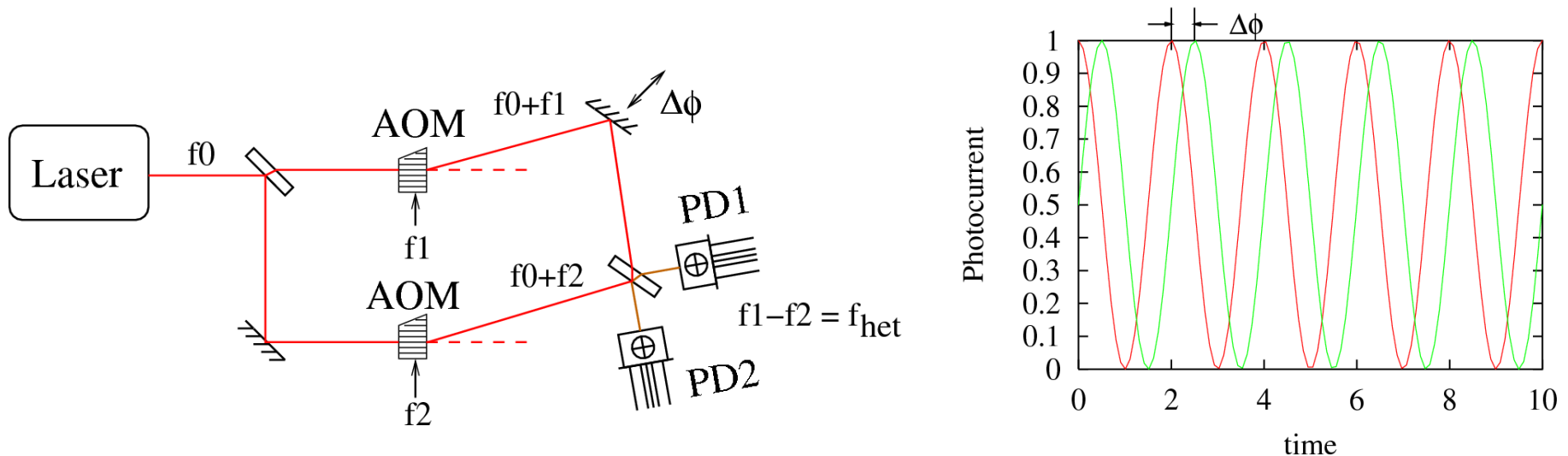
# Ifo requirements



- Very simple requirements, self defined
- Pathlength noise  $9 \text{ pm}/\sqrt{\text{Hz}}$  with freq. dependence
- Was assumed to be sufficient for the LISA local readout



# Interferometer principle

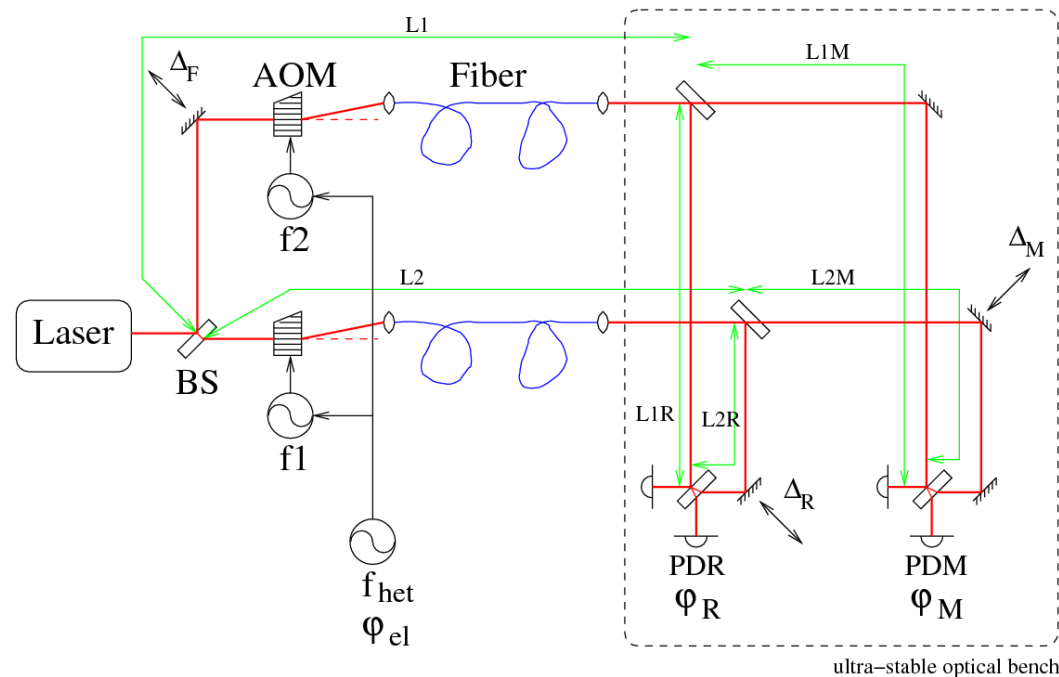


- audio-frequency heterodyne Mach-Zehnder
- independent of operating point
- wide dynamic range (many fringes)
- no lock acquisition needed, immediately ready after power-on.
- phase measurement needs no calibration, conversion to length is laser wavelength (known and constant)





# Reference subtraction

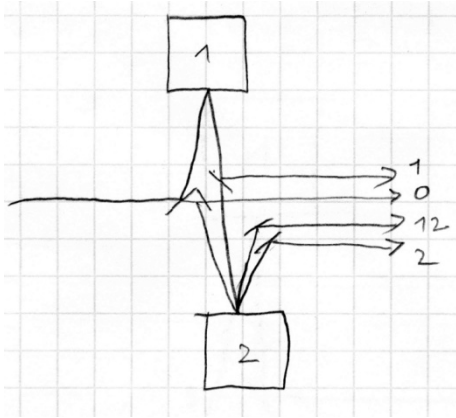


- Each photodiode measures Pathlength difference, starting from first BS
- External contributions must be subtracted via stable reference interferometer
- subtraction is imperfect, hence phase of Ref. Ifo (“OPD”) must be stabilized (*later finding*)

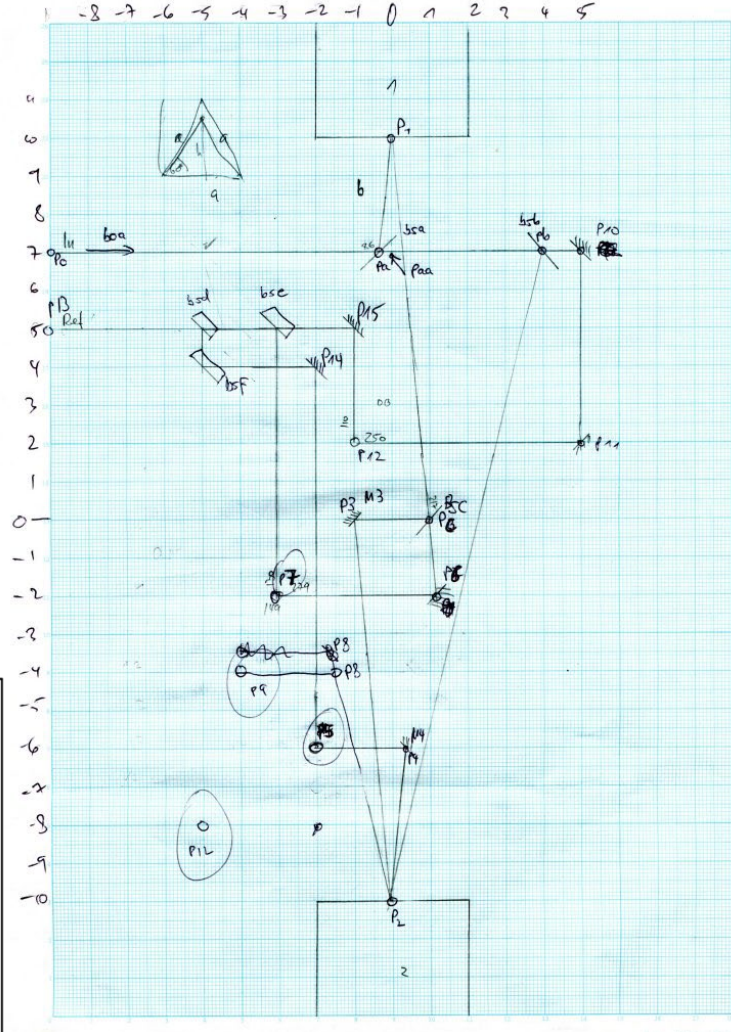




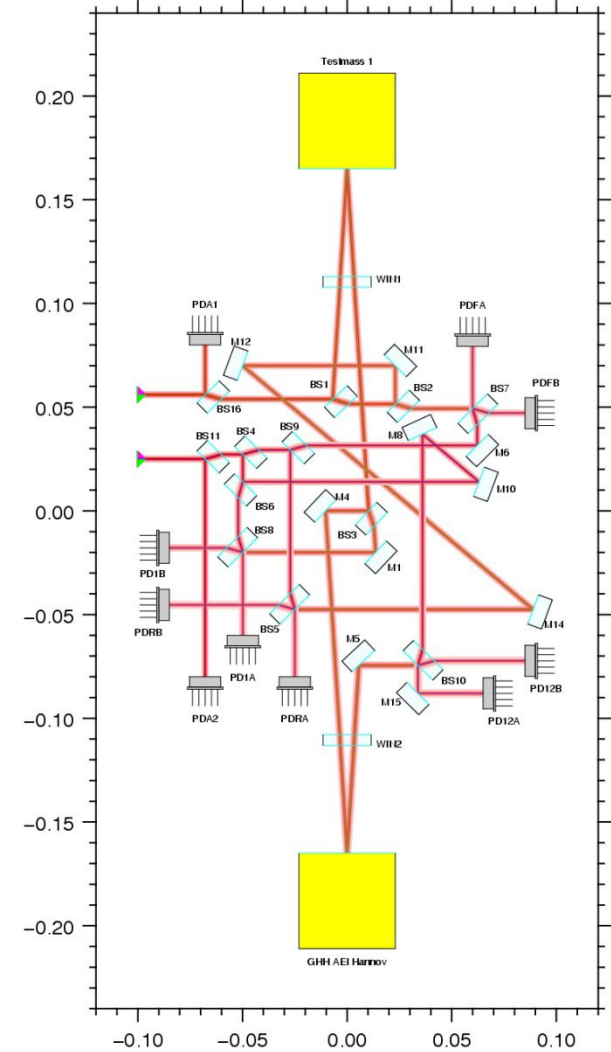
# The LTP Interferometer



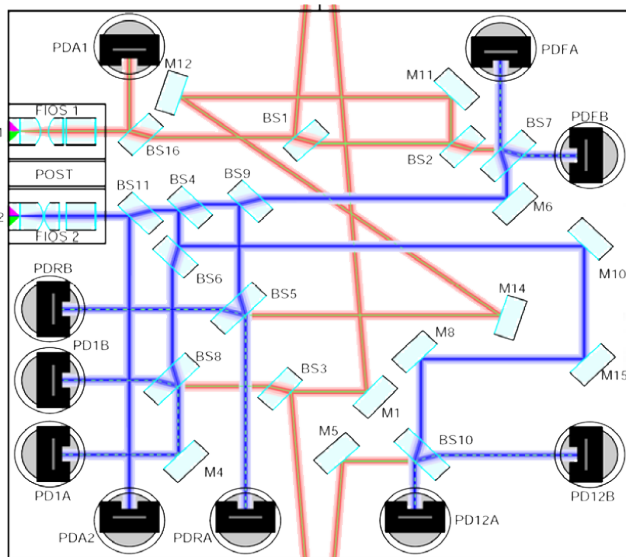
2001



2001



2003

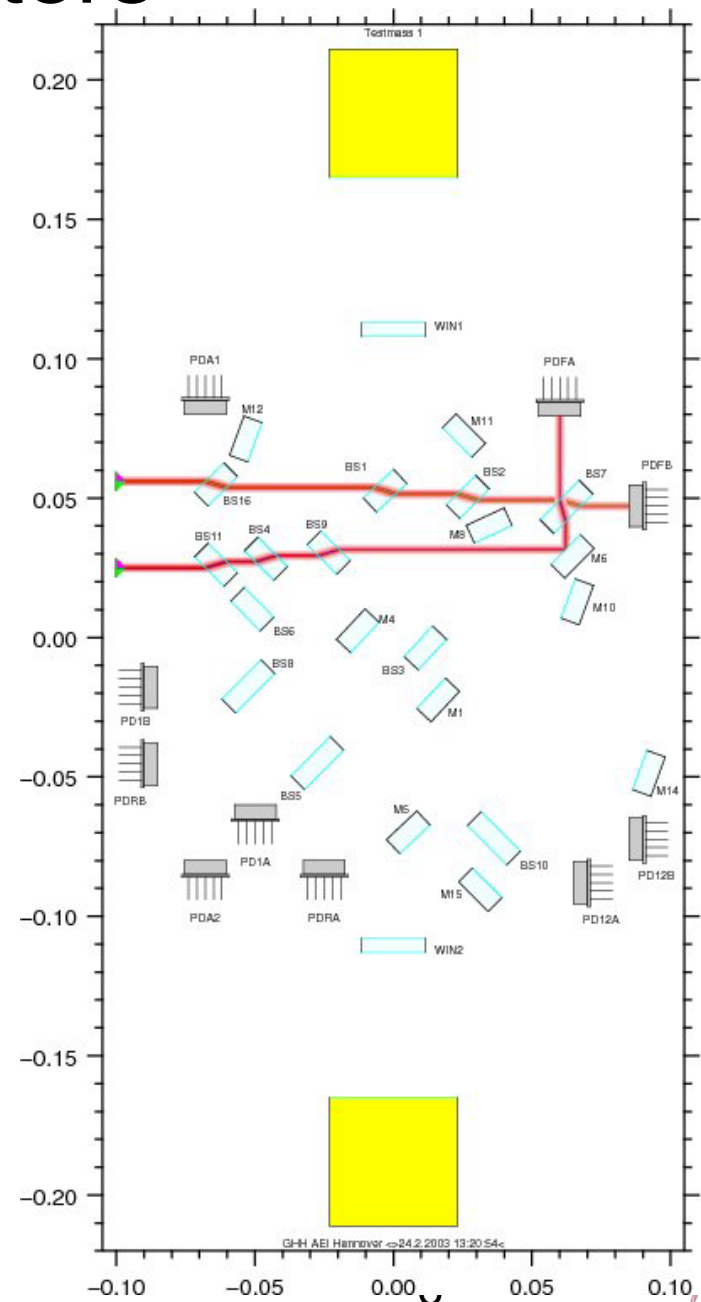


2006



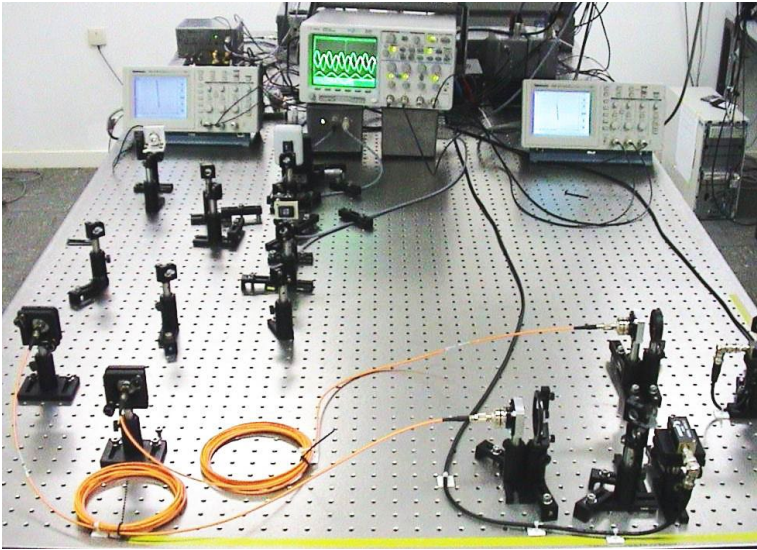
# 4 interferometers

- TM1 position and orientation w.r.t. optical bench
- TM2 position w.r.t. TM1, TM2/TM1 orientation w.r.t. optical bench
- Reference phase
- Frequency noise via unequal pathlengths

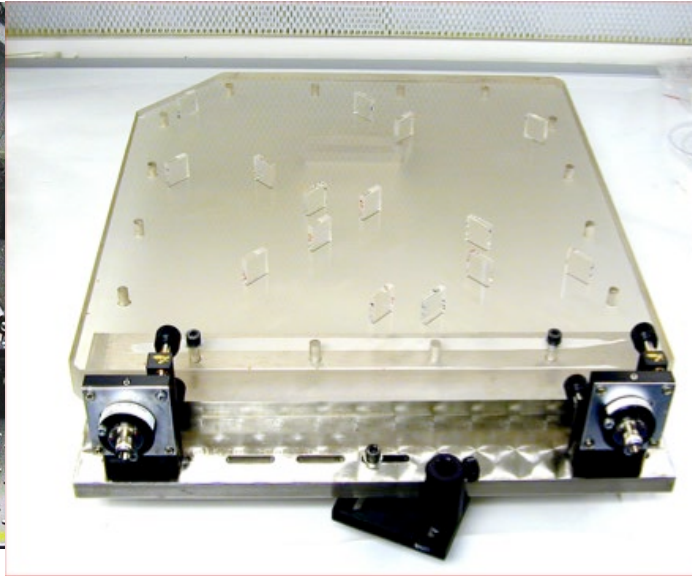




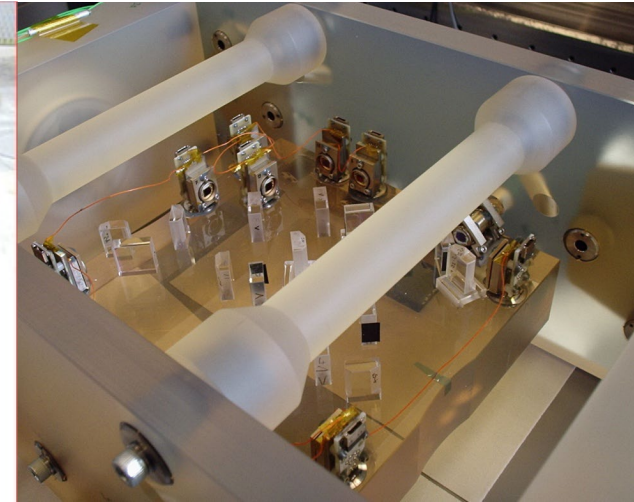
# The LTP Interferometer



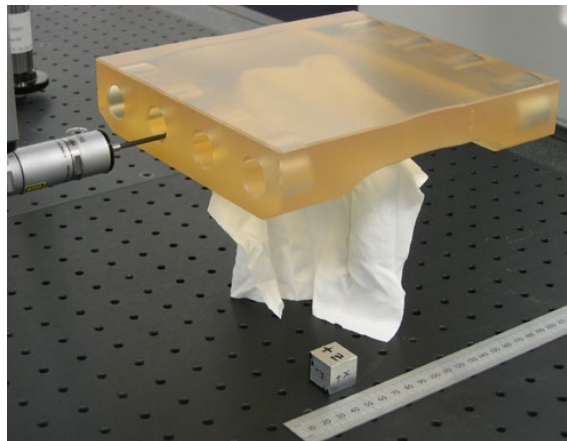
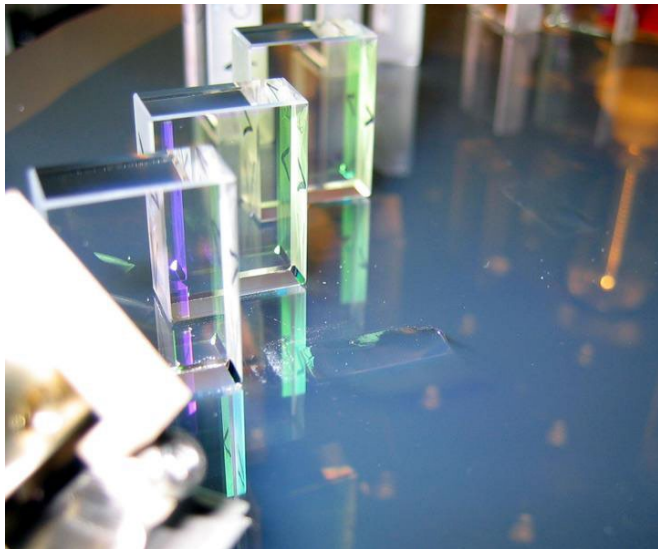
2001



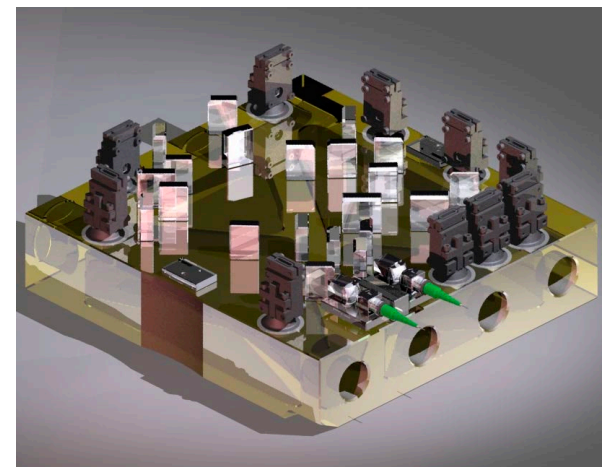
2002



2003



2007



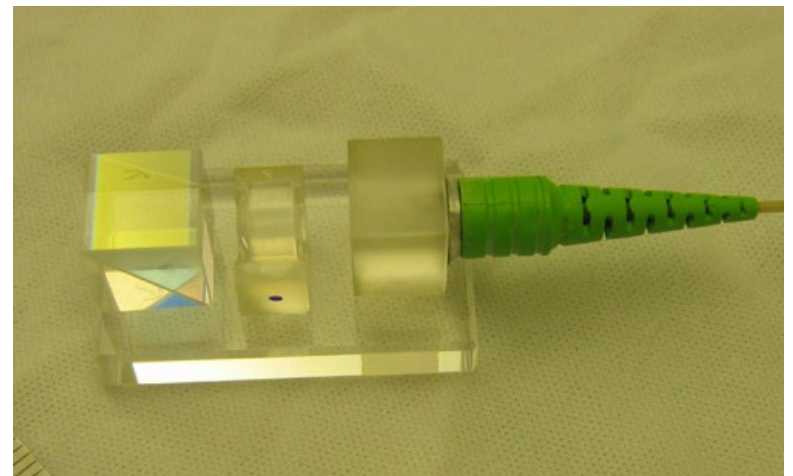
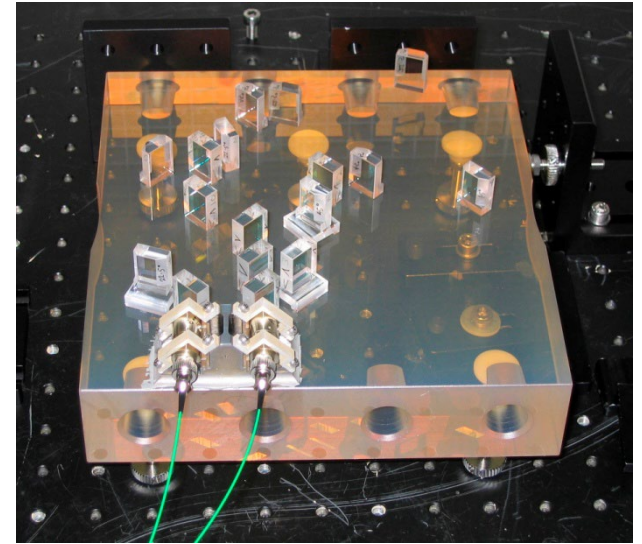
2007





# Optical bench

- 20\*20cm Zerodur baseplate
- hydroxycatalysis bonding
- about 30 components
- 4 interferometers
- challenges:
  - vertical alignment
  - fiber launchers
  - absolute alignment w.r.t. test mass housing





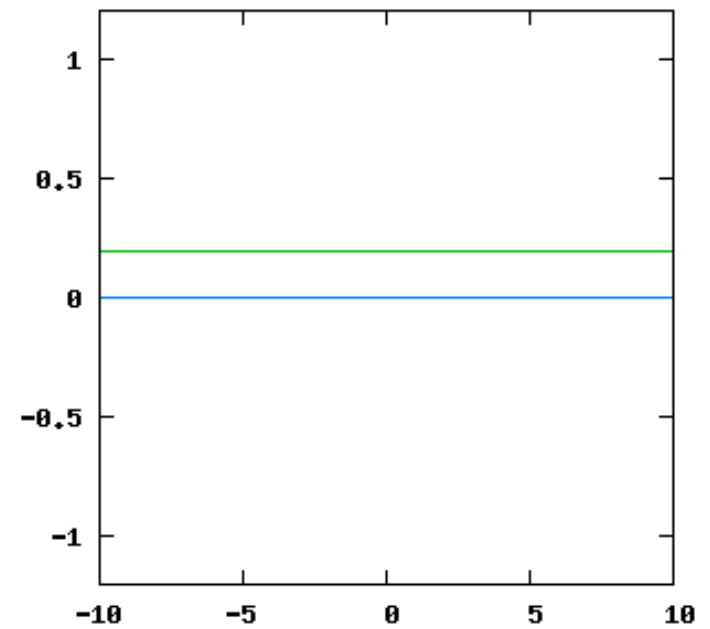
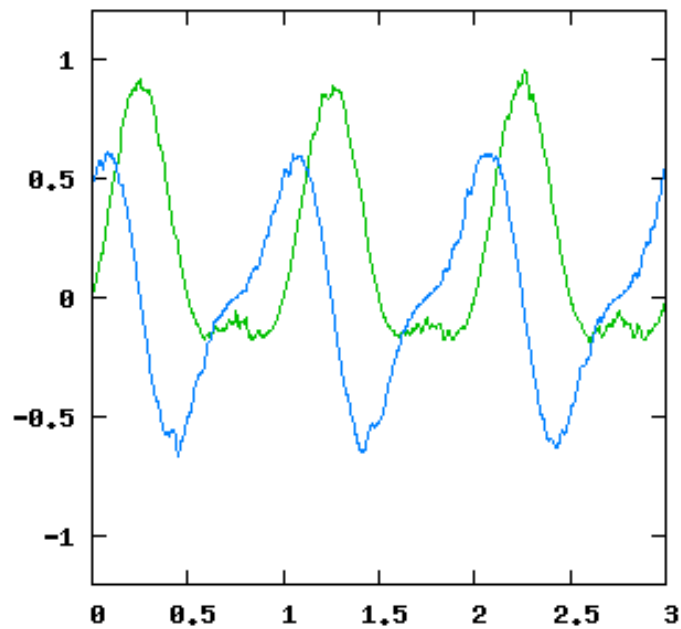
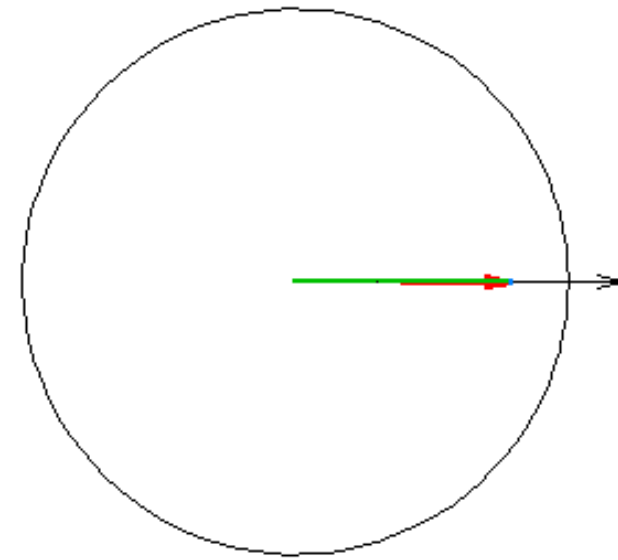
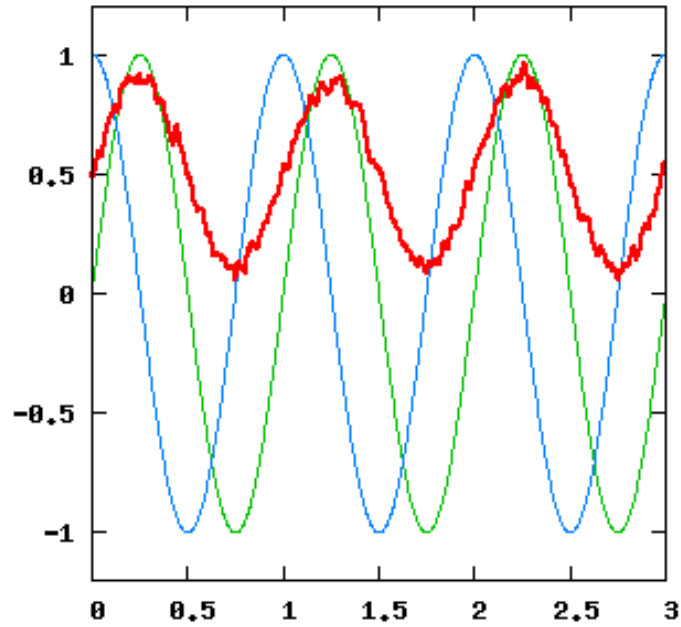
University  
of Glasgow



UNIVERSITY OF  
BIRMINGHAM



# Phasemeter





# Phasemeter

## Phasemeter using SBDFT (Single-Bin Discrete Fourier Transform)

Inputs from one quadrant diode:  $x_i = U_A(t_i)$ , same for  $U_B(t), U_C(t), U_D(t)$ .

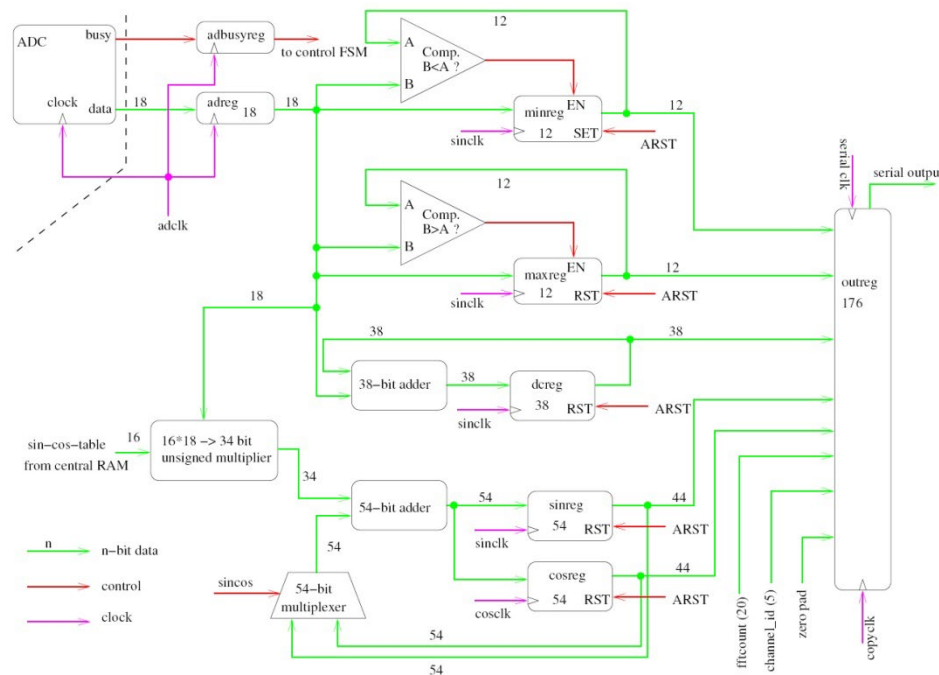
First step: **SBDFT** contains  $> 99\%$  of the computational burden:

$$\text{DC components: } DC_A, DC_B, DC_C, DC_D \quad (\text{real}) : \quad DC_A = \sum_{i=0}^{n-1} x_i,$$

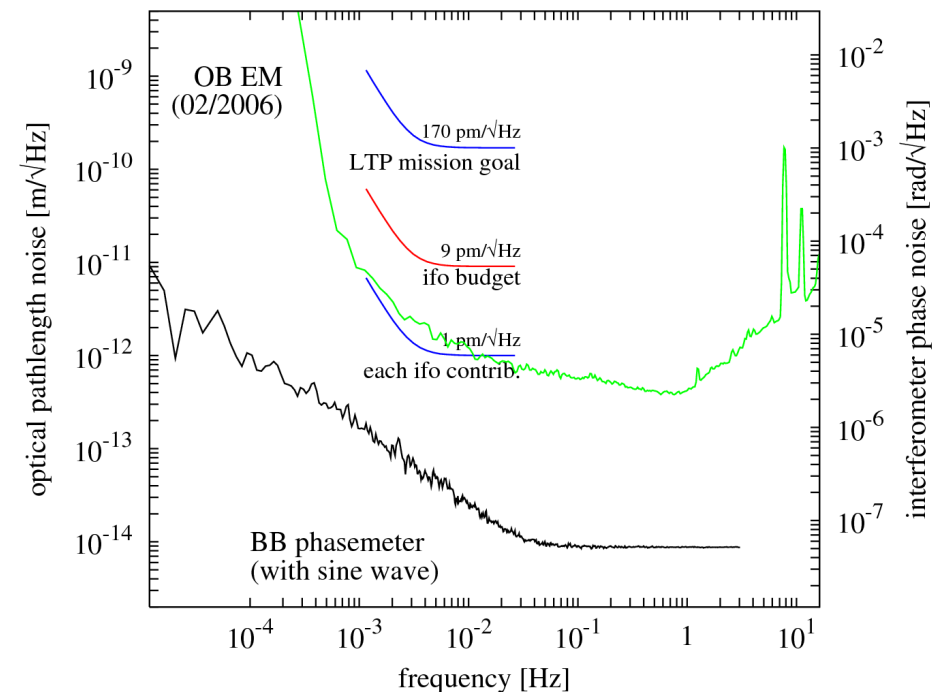
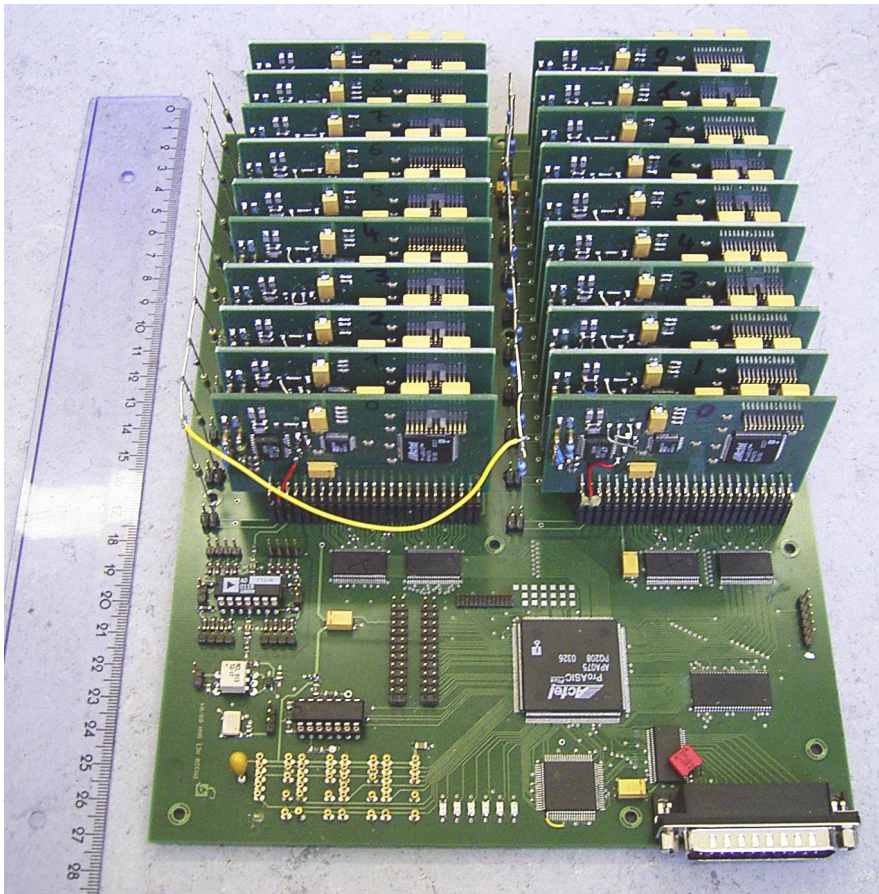
$$f_{\text{het}} \text{ components: } F_A, F_B, F_C, F_D : \quad \Re(F_A) = \sum_{i=0}^{n-1} x_i \cdot c_i, \quad \Im(F_A) = \sum_{i=0}^{n-1} x_i \cdot s_i.$$

The constants  $s_i$  and  $c_i$  are pre-computed:  $c_i = \cos\left(\frac{2\pi i k}{n}\right)$ ,  $s_i = \sin\left(\frac{2\pi i k}{n}\right)$ .

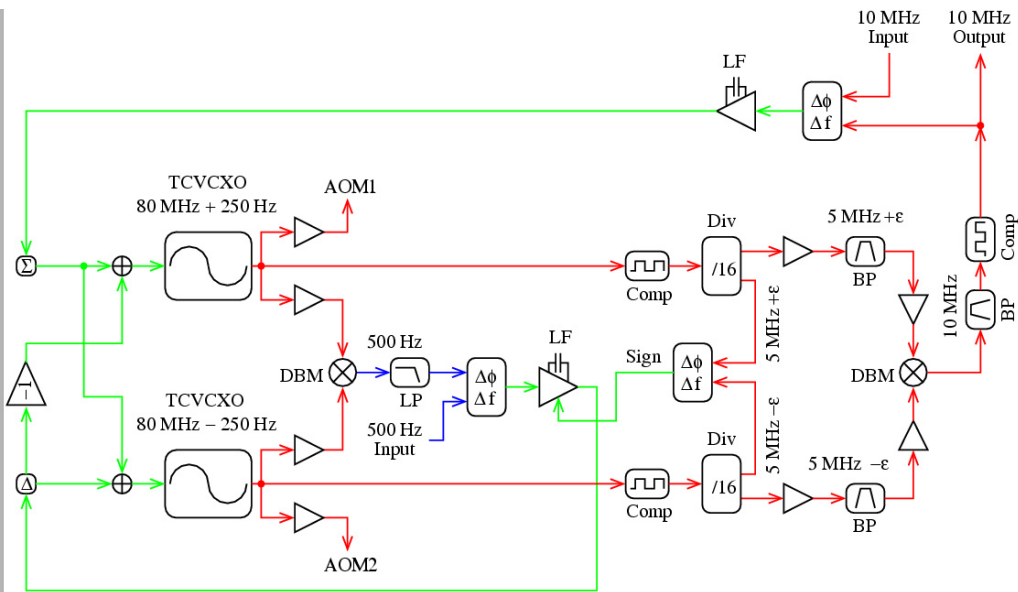
### FPGA



# Phasemeter prototype 2005



# Frequency synthesizer



TCVCXO = temperature compensated voltage controlled crystal oscillator

LP = lowpass filter

BP = bandpass filter

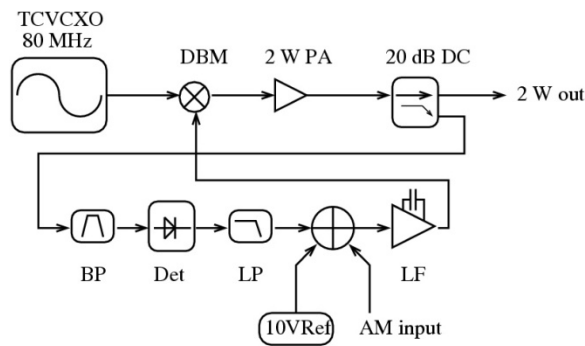
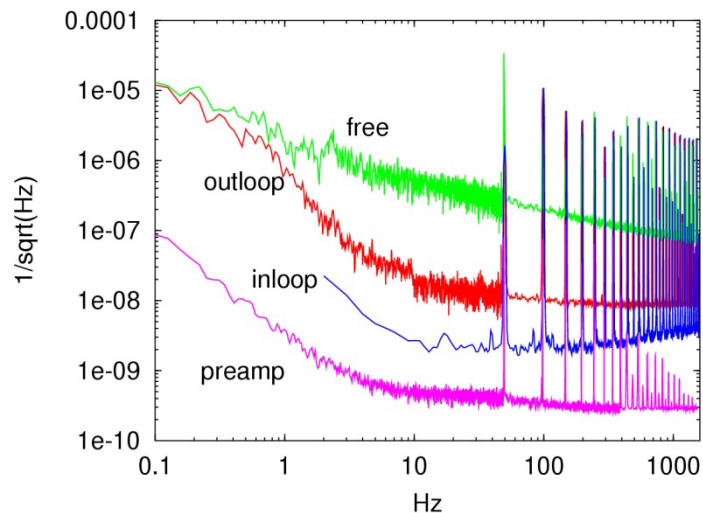
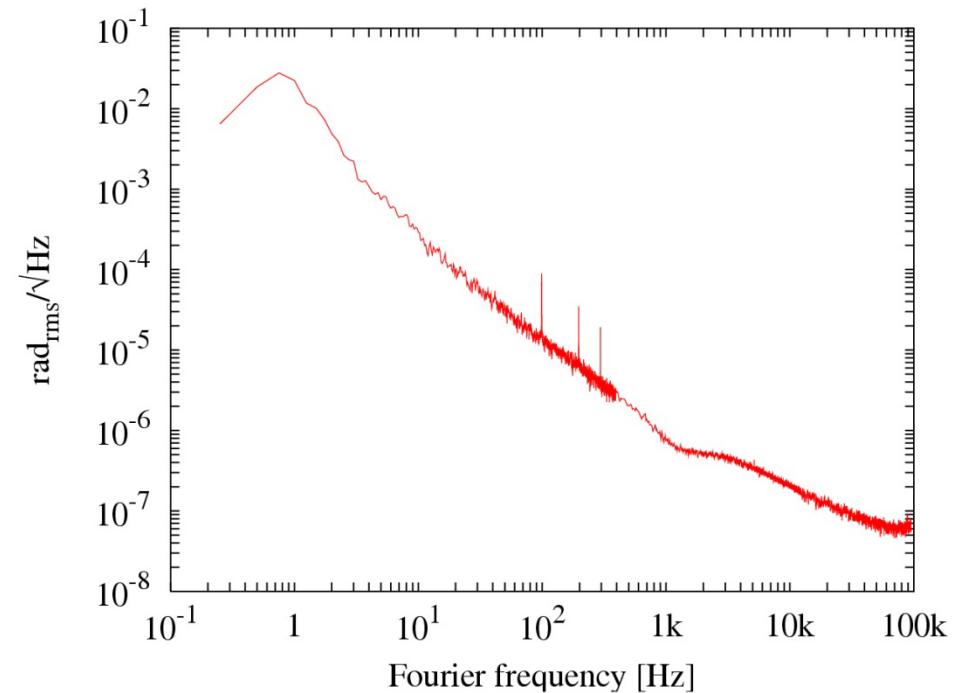
LF = loop filter

Comp = comparator to generate logic level signals

Div = digital frequency divider

DBM = double balanced mixer

$\Delta\phi\Delta f$  = digital phase/frequency detector



TCVCXO = Temp. compens. VCXO

DBM = double balanced mixer (used as attenuator)

PA = Power Amplifier

DC = Directional Coupler

BP = 80 MHz Bandpass

Det = Schottky Detector

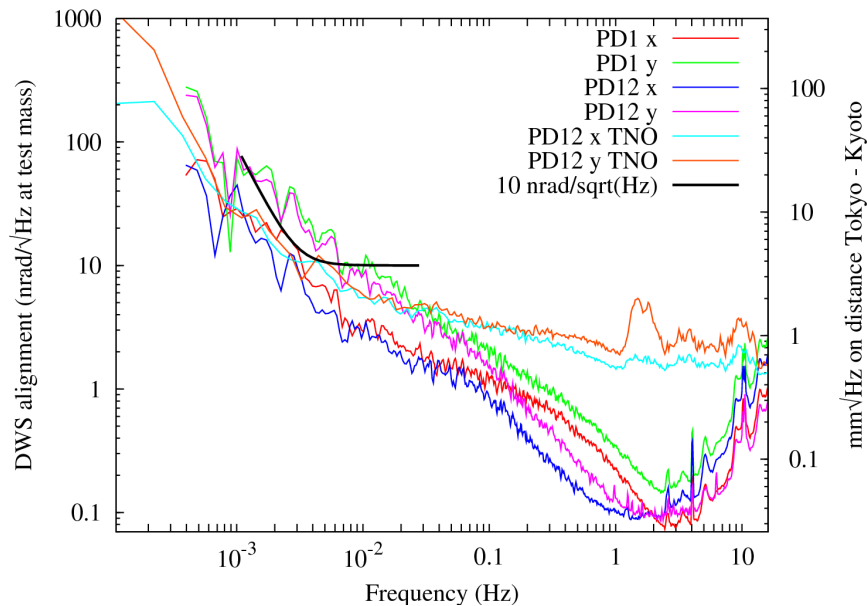
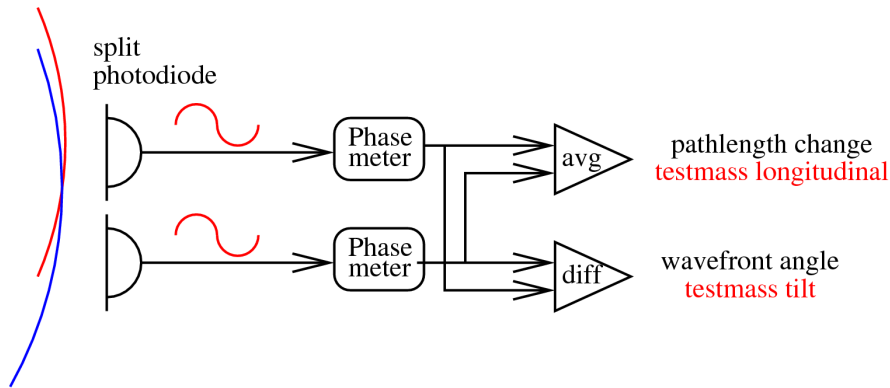
LP = 10 MHz Lowpass

LF = Loop Filter





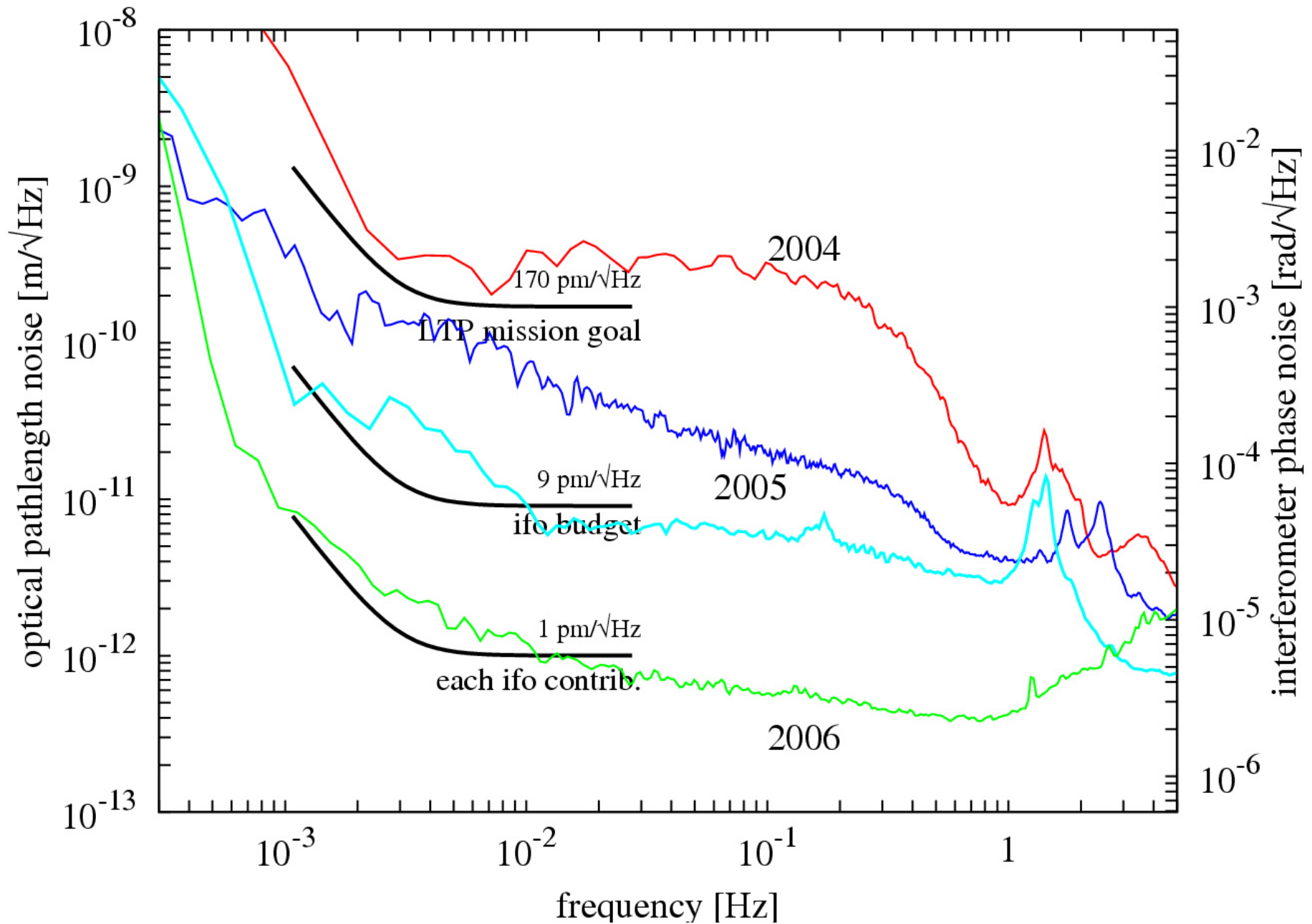
# Angle measurements



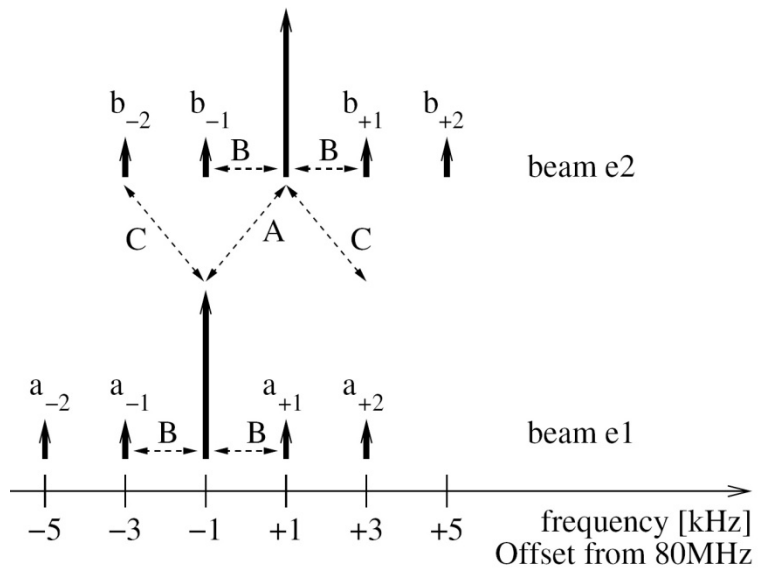
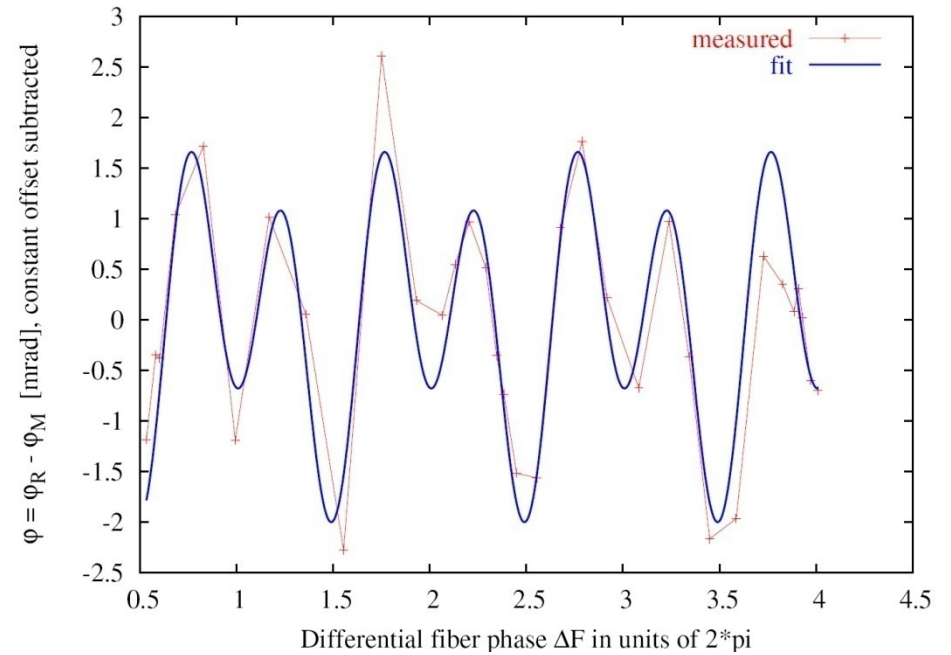
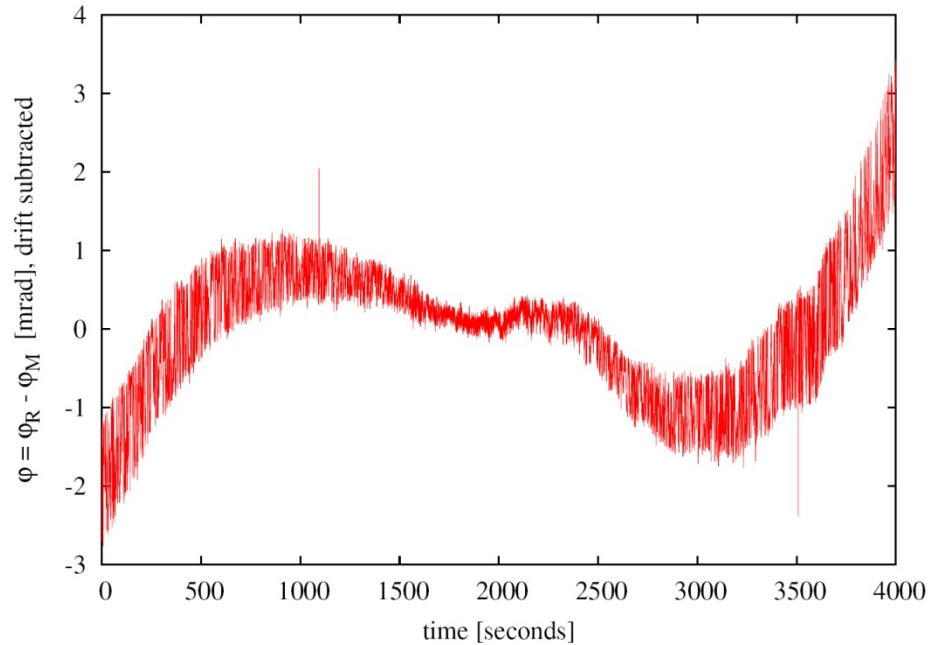
- uses Differential Wavefront Sensing (DWS)
- large amplification TM angle to audio phase difference (about 5000)
- one quadrant diode is enough, no reference needed
- immune to several noise sources
- excellent sensitivity



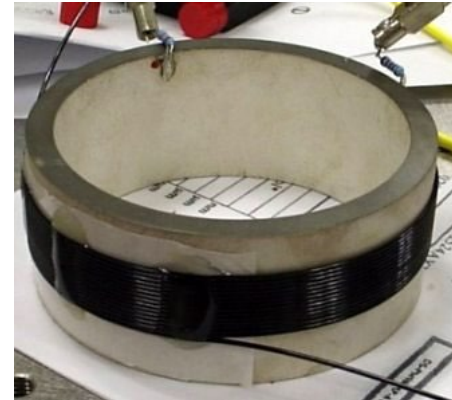
# LTP Interferometer Sensitivity



# Unexpected noise



$$\begin{aligned} \frac{\delta\varphi}{\varepsilon} &= \sin(\varphi_M + \gamma) - \sin(\varphi_R + \gamma) \\ &= 2 \cos\left(\Delta_F + \frac{\Delta_M + \Delta_R}{2} + \gamma\right) \cdot \sin\left(\frac{\Delta_M - \Delta_R}{2}\right) \\ &= 2 \cos\left(\frac{\varphi_M + \varphi_R}{2} + \gamma\right) \cdot \sin\left(\frac{\varphi_M - \varphi_R}{2}\right). \end{aligned}$$





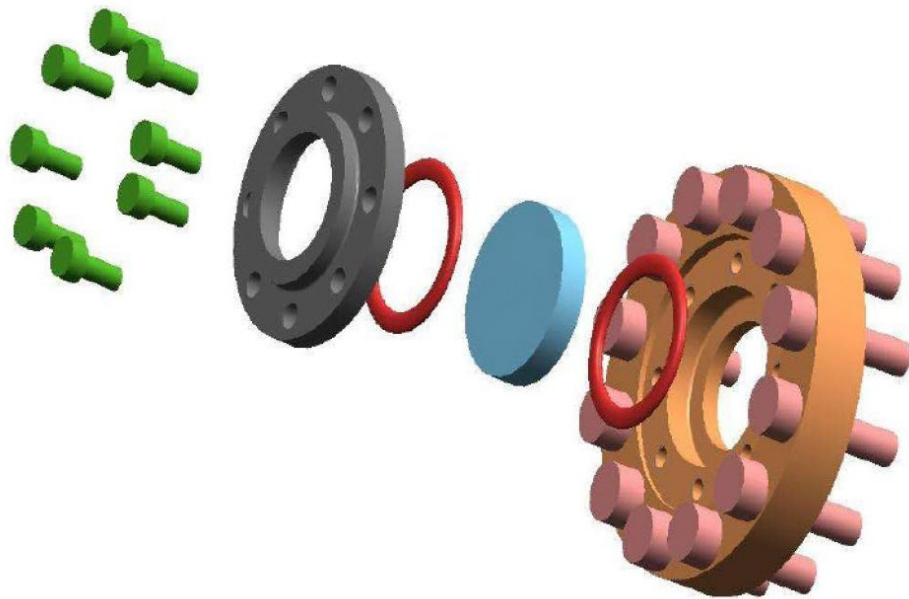
# „small vector“ noise

---

- Caused by EMI crosstalk in prototypes
- Mitigated twice in FM:
  - stringent crosstalk requirements
  - OPD stabilization
- Result: this noise is invisible in flight



# Optical Window

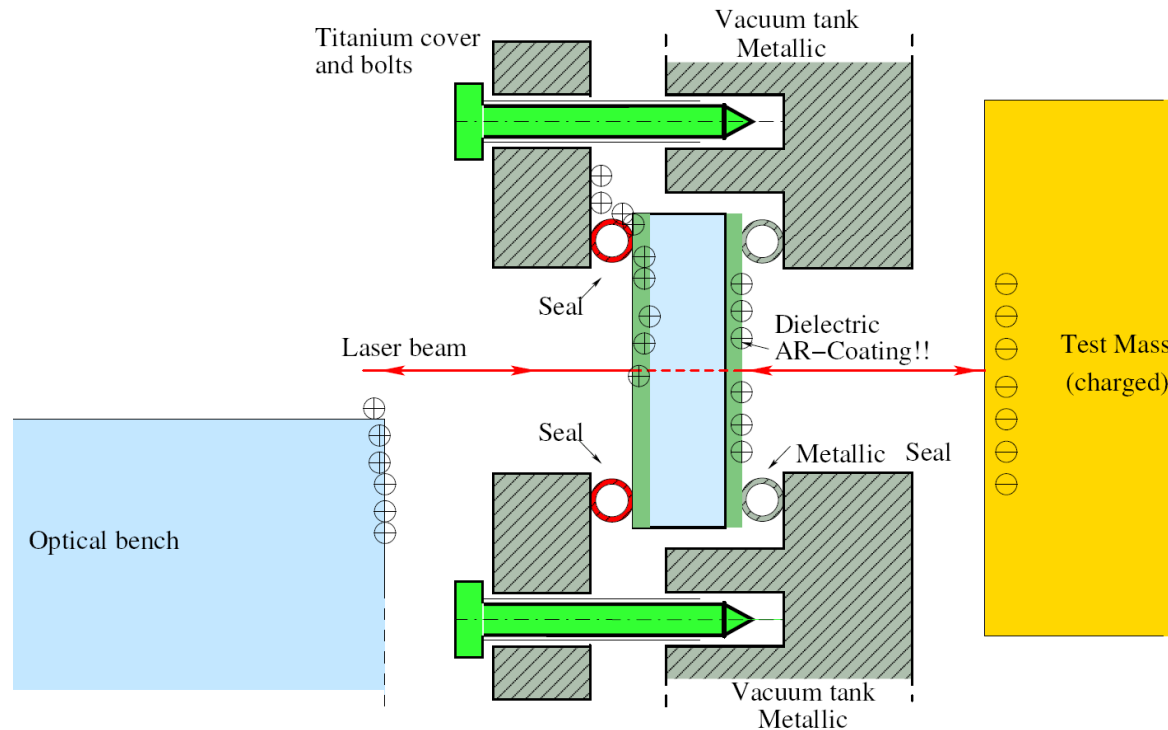


- needed for optical access of interferometer beams
- like a flange of vacuum tank
  - optical pathlength in transmission 12mm/24mm
- “athermal” glass S-PHM52 (Ohara) minimizes pathlength error  $dn/dT + (n-1)\alpha$
- extensive testing at AEI for radiation hardness, pressure-dependent pathlength error and actual performance was successful.



# Optical window electrostatics

an isolating window may accumulate charges  
and disturb the test mass



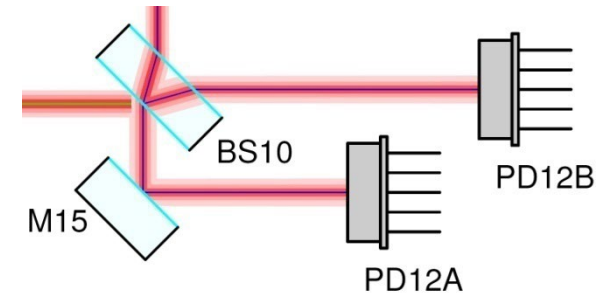
Solution: apply conductive ITO ( $\text{In}_2\text{O}_3/\text{SnO}_2$ ) layer to optical window





# Error handling

- redundant photodiodes and phasemeter
- occasional temporary failures by high-energy protons are expected
- advance planning for the most probable error cases
- nominal operations is 20% of the software effort, error treatment 80% !



## Name

overrange (value > max)

underrange (value < min)

crc-check

delta-check

epsilon-check

Latch-up (L)

Transmission (T)

PM configuration register

PM LUT checksum

PM state of health

Over-Run (O)

MIL-Bus error (all MIL-Bus reasons for incorrect data reception)

Ground commanded channel disable

## Acronym

overrange\_ $\{i, j, k\}$

underrange\_ $\{i, j, k\}$

crc\_ $\{i, j, k\}$

delta\_ $\{i, j, k\}$

epsilon\_ $\{i, j, k\}$

L\_ $\{i, j, k\}$

T\_ $\{i, , k\}$

PM\_config

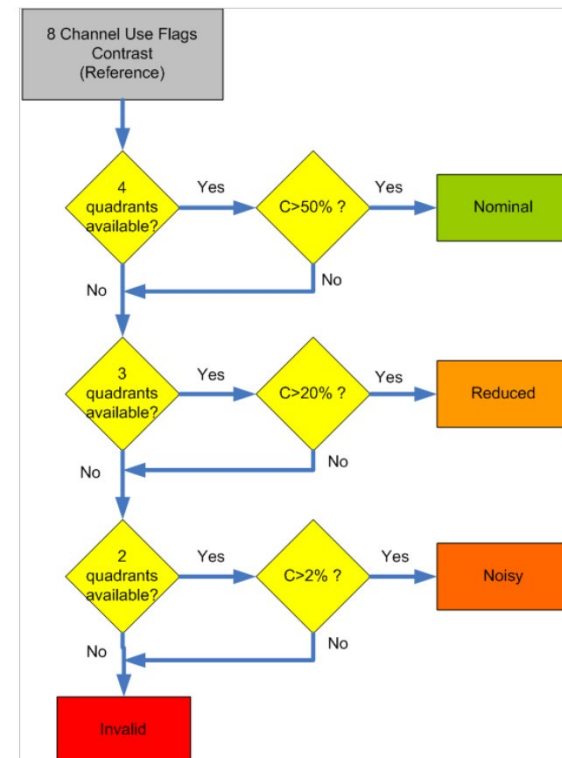
PM\_LUT

PM\_healthstate

overrun\_ $\{i, , k\}$

Milbus\_error

gccd\_ $\{i, j, k\}$



# Clock synchronization

Without synchronization, the 100 Hz within the LTP and the 10 Hz of the DFACS would invariably slowly drift against each other. Consequently, every now and then either the 9<sup>th</sup> or the 11<sup>th</sup> sample would be picked instead of the 10<sup>th</sup> sample. At this time the data age jumps by 10 ms.

Even if such jumps were within the formal specifications of the DFACS system, it is well possible that they would produce artefacts in the science data, in particular if they occur at more or less regular intervals. Simulations of this effect at ASD are under way.

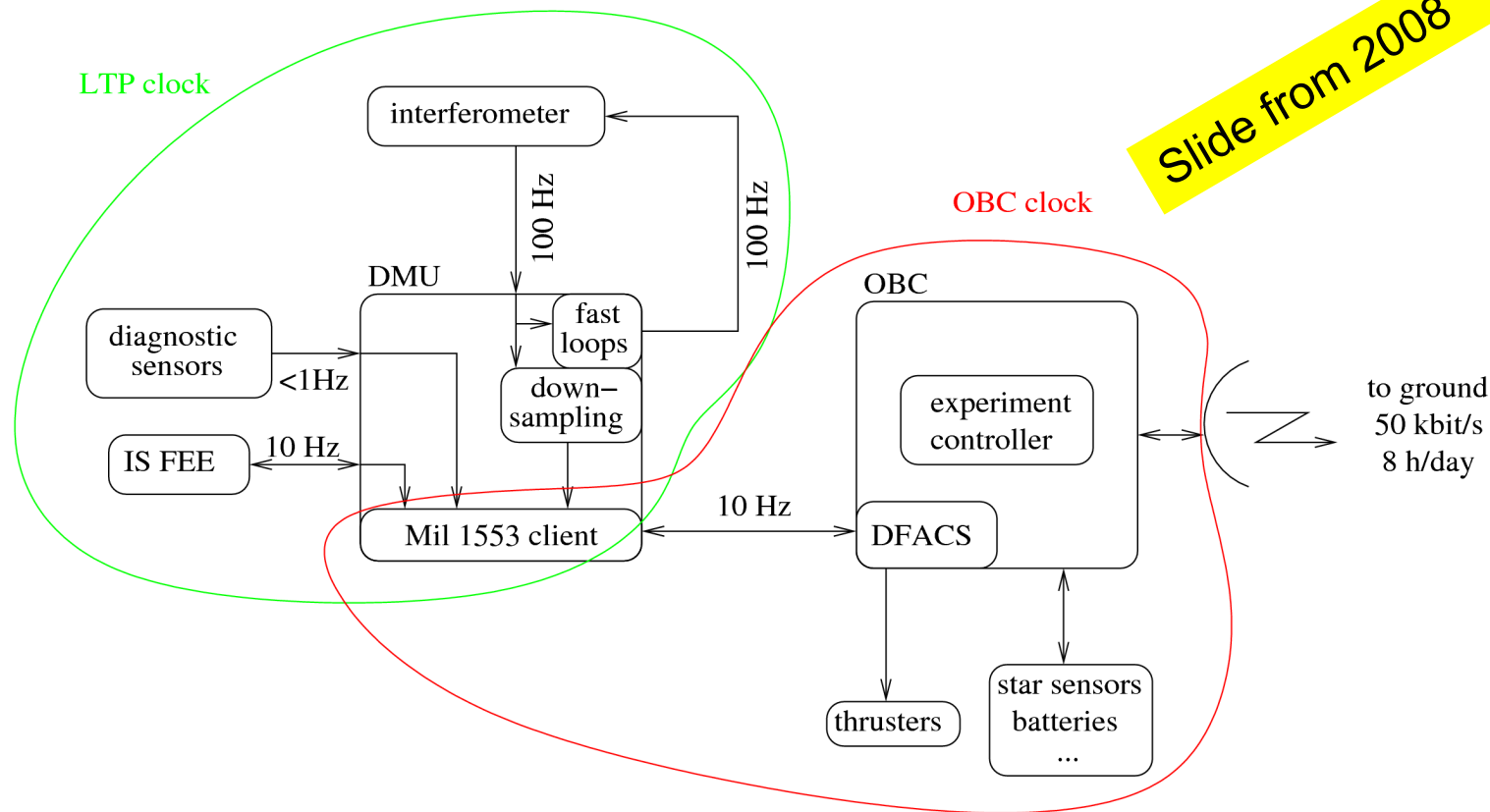
## 4 Conclusion

TN from 2005

Although we cannot prove with absolute certainty that synchronization is necessary to achieve the scientific mission goals, there are compelling arguments for synchronization.



# Data flow

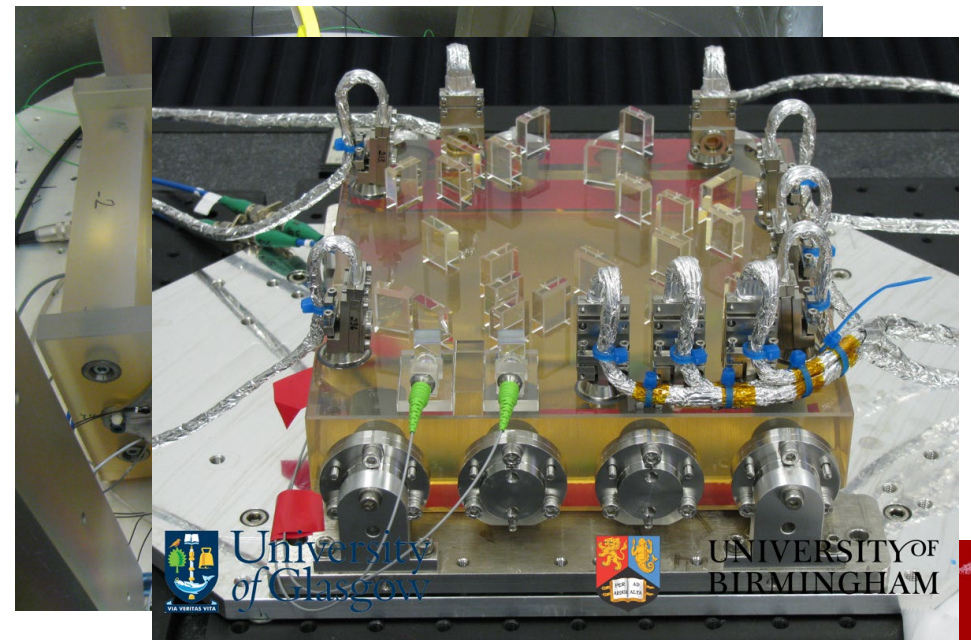
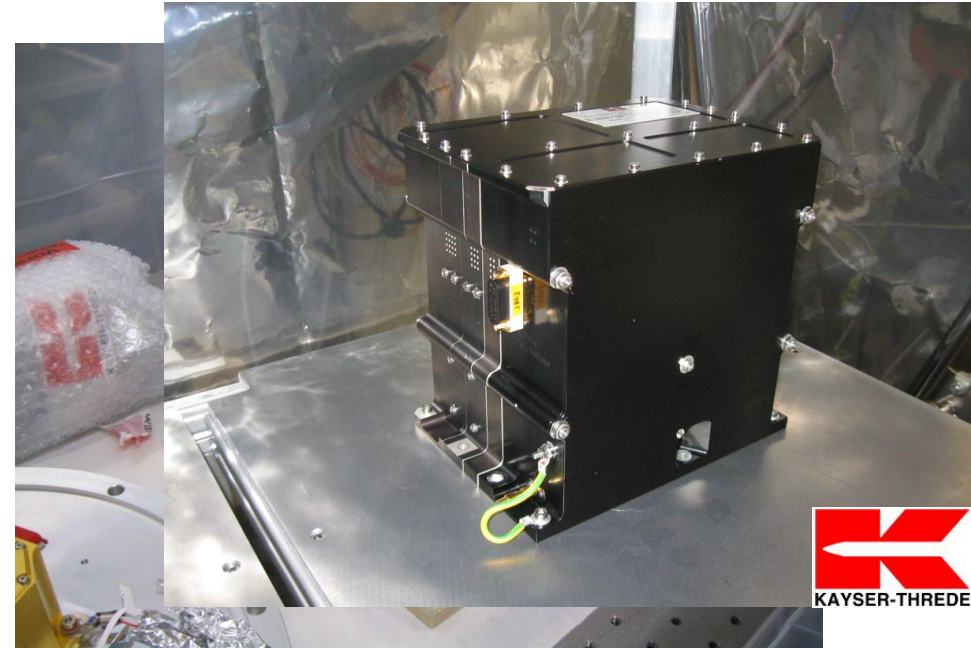
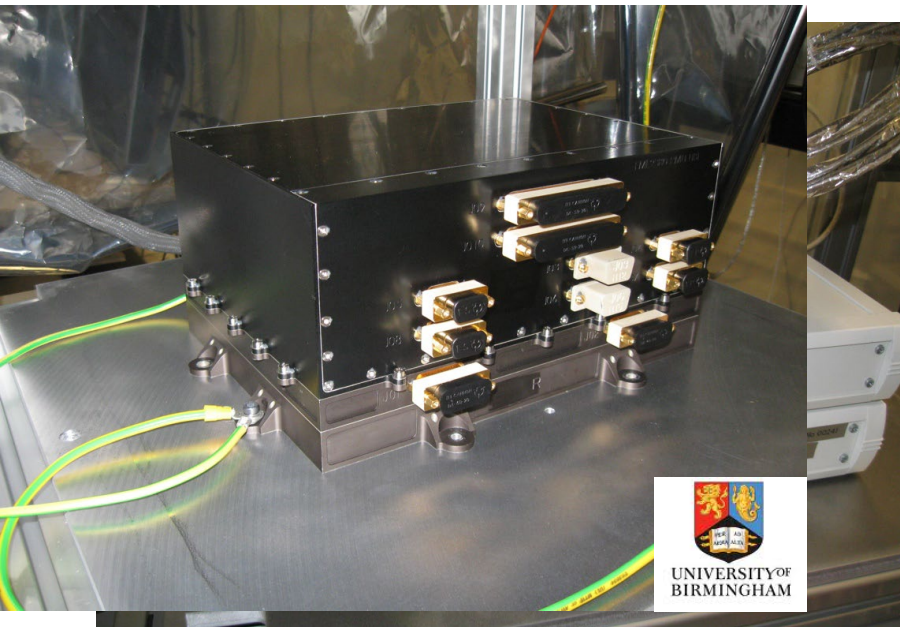


- On-board computer (OBC) does not deliver its clock
- LTP runs on nominally same frequency but not synchronized
- drag-free requires continuous intimate interaction between them
- non-synchronous operation creates many problems

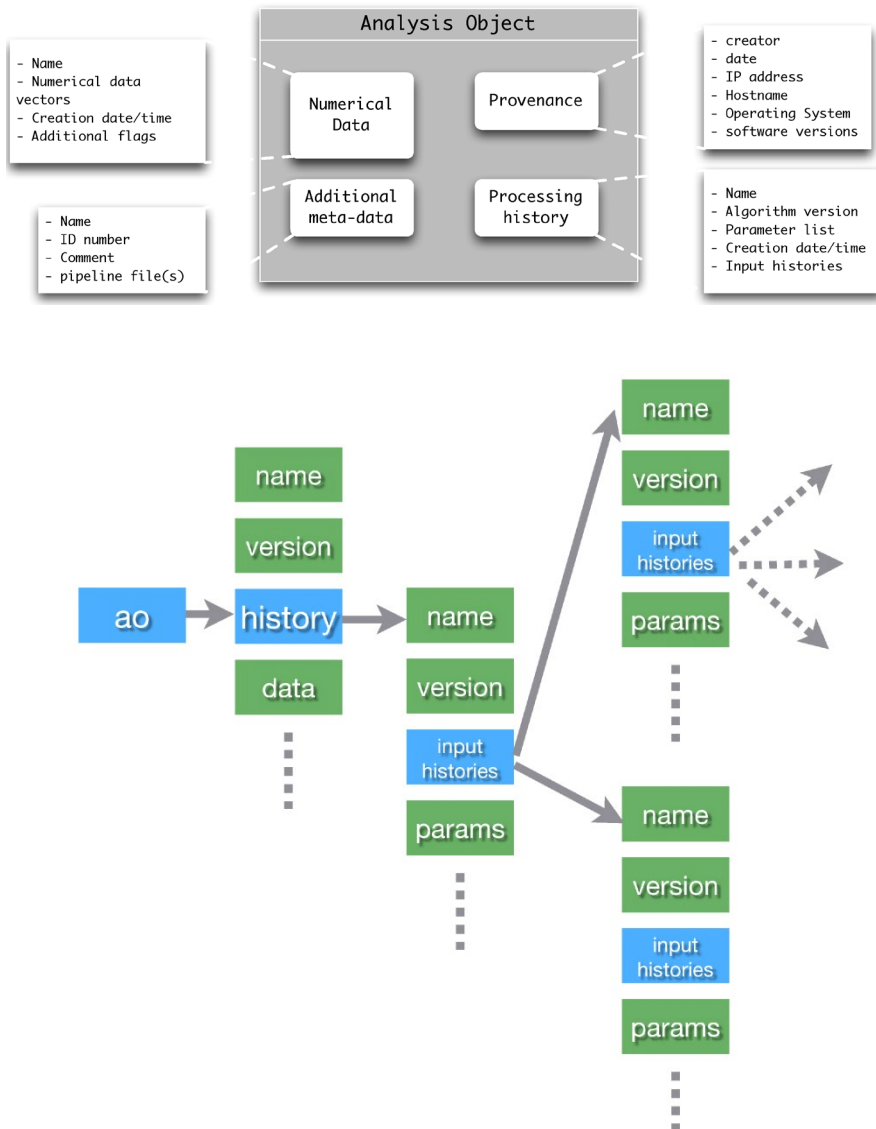




# From prototypes to Ems and FMs



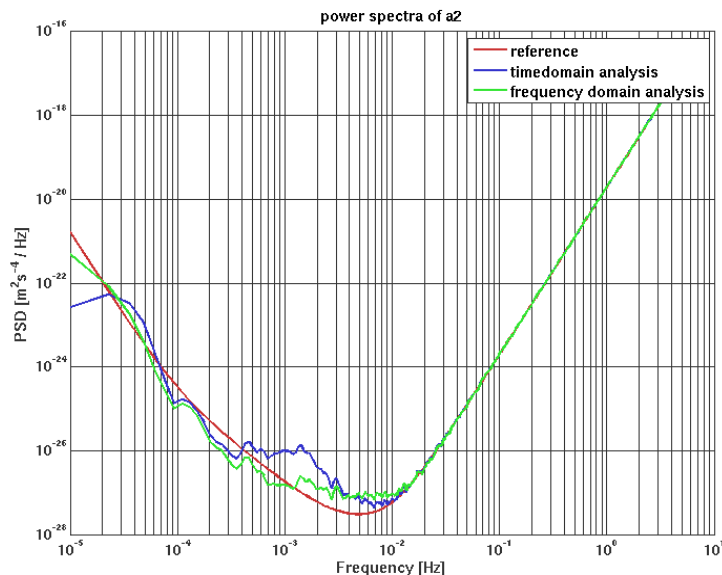
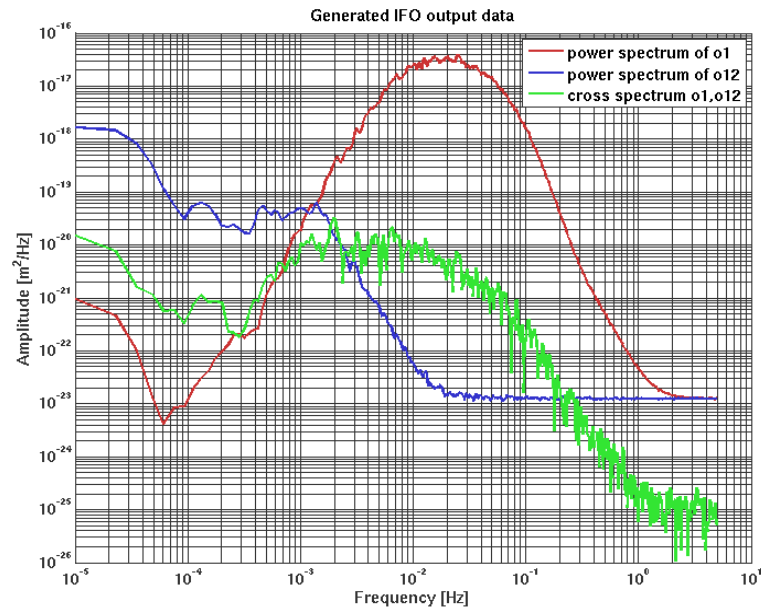
# LTPDA: Analysis objects



- A useful result is **not** a graph or a file full of ASCII data
- Each result must “know” how it was produced with all details
- Each result can be reproduced by any user with access to the raw data, also with modified processing
- All intermediate steps and final results are stored as MATLAB structures called “Analysis objects” (AO)
- Each processing step appends its name, version and parameters to the history of the resulting AO



# Mock data challenge

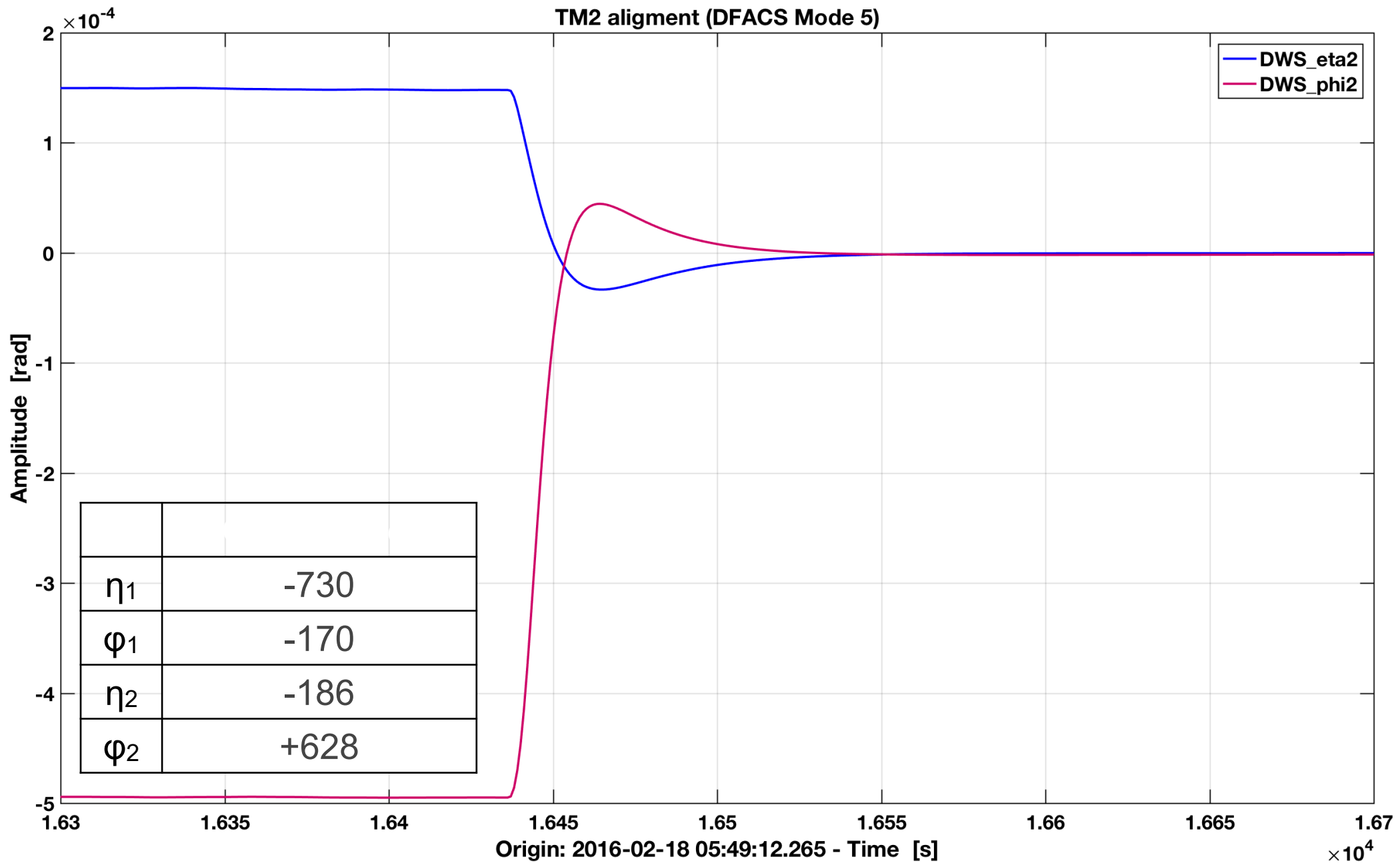


- Test of the data analysis pipeline:
- One team generates downlink data with a spectrum kept secret
- Second team uses LTPDA to recover the spectrum
- First round (simple model) successfully concluded

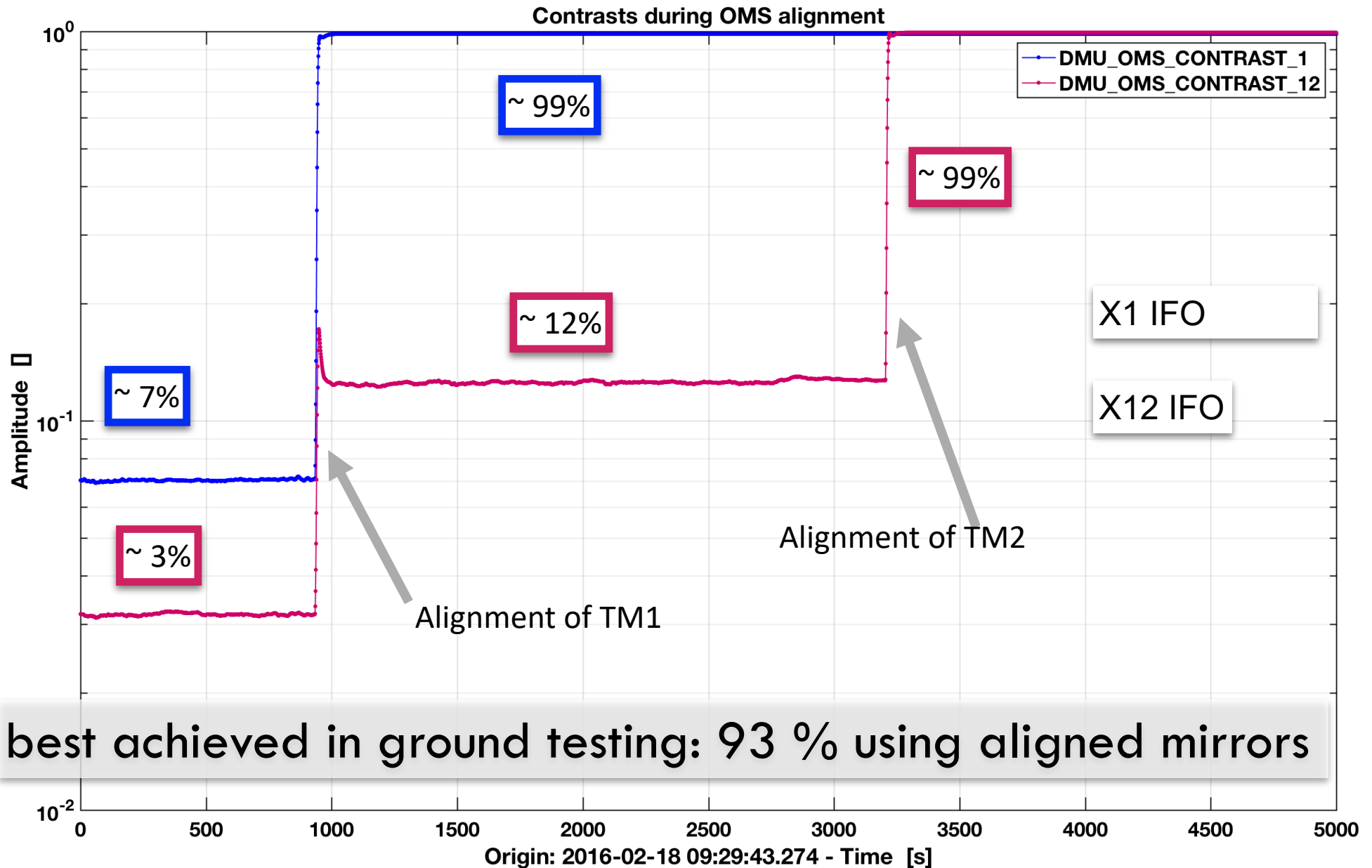




# Finally ... In orbit

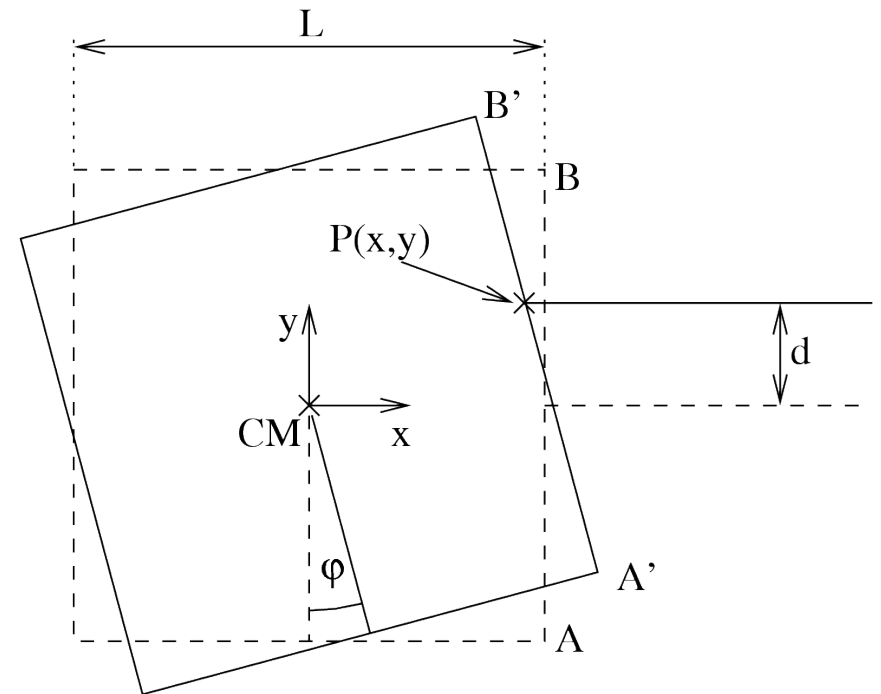


# Contrasts before and after alignment



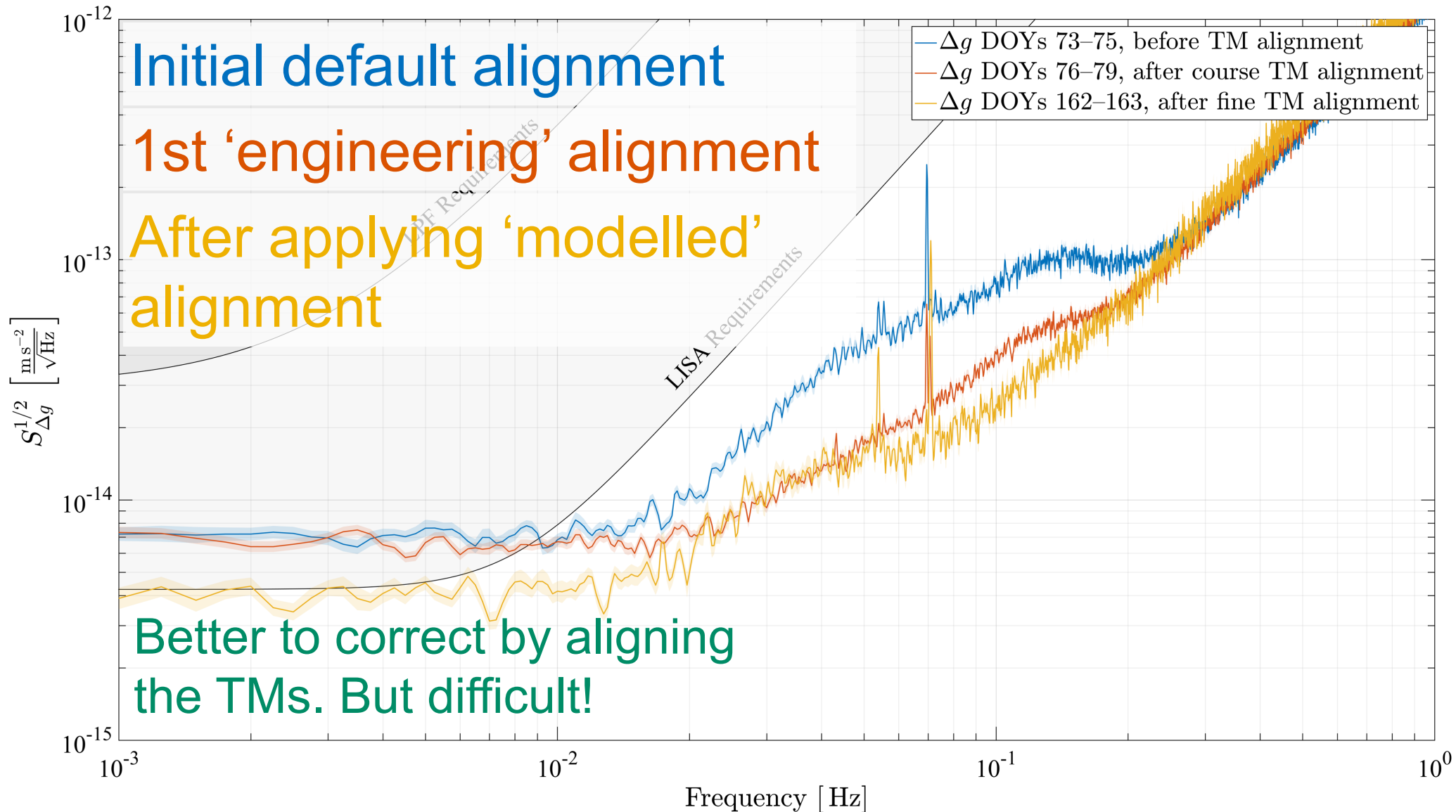
# Cross coupling of other degrees of freedom

- A perfect interferometer **would** measure only  **$x$**
- An offset  **$d$**  couples rotations of test mass or spacecraft into  **$x$**
- An misalignment angle  $\phi$  couples  **$y/z$**  motion into  **$x$** .
- depends on geometry of the interferometer and beam parameters (curvature etc.)



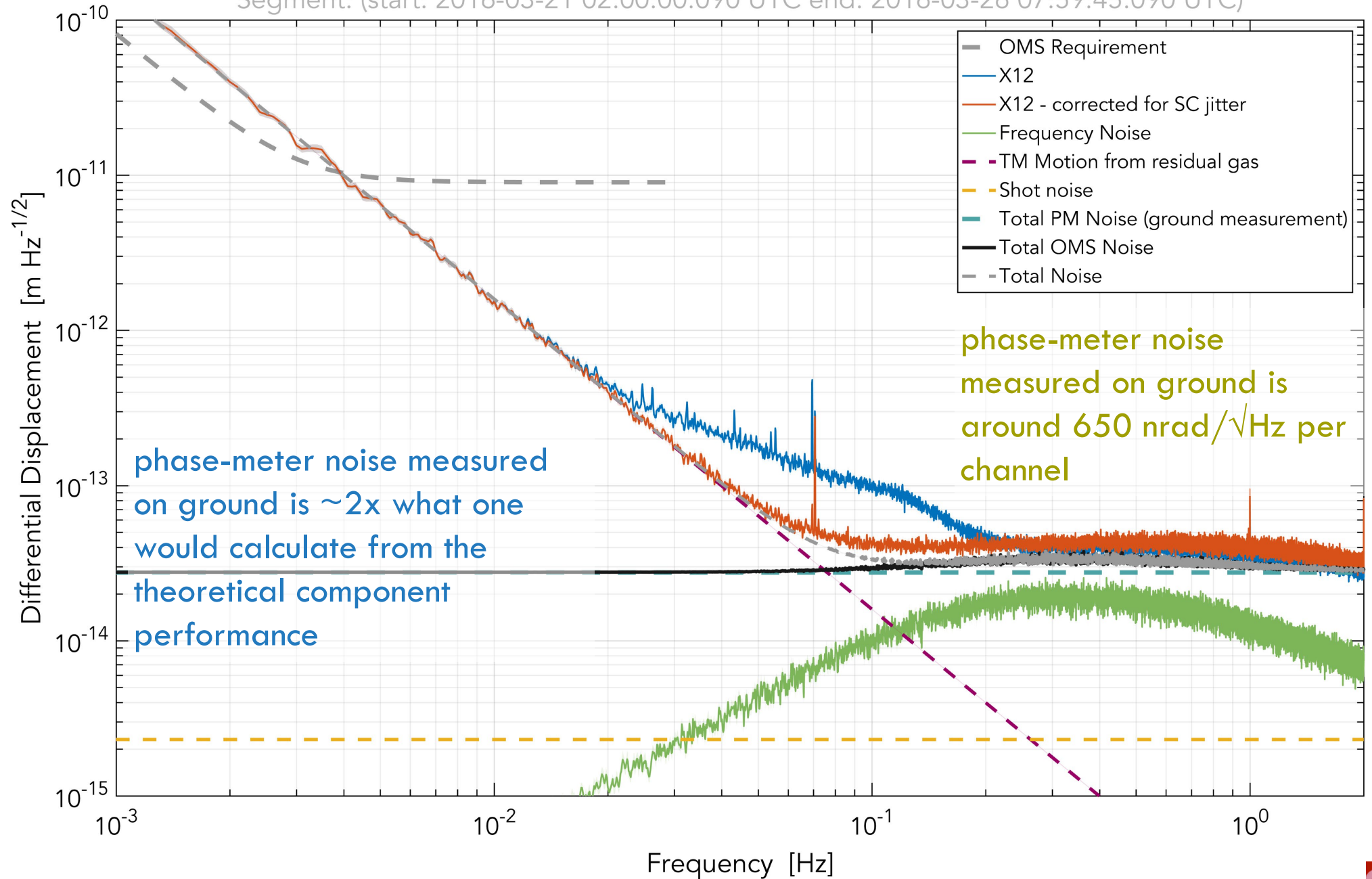


# Cross-talk in raw $\Delta g$ – TM alignment

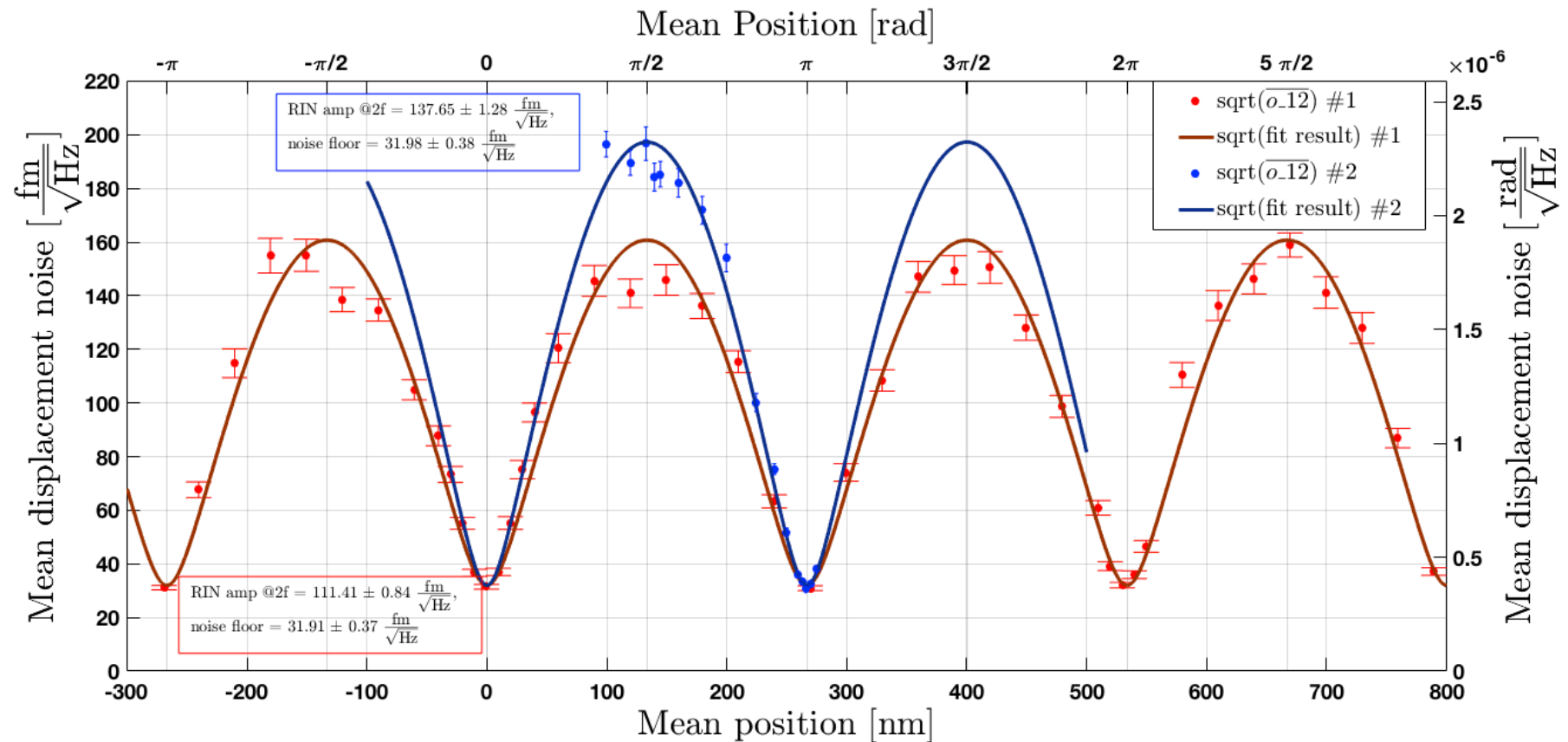


# In-flight Ifo noise

Segment: (start: 2016-03-21 02:00:00.090 UTC end: 2016-03-26 07:59:45.090 UTC)



# In-flight Experiment



The ultra low noise in flight allowed to investigate minor effects below the requirements, but relevant for LISA:

- RIN @ DC, 1f, 2f
- Stability of optics in orbit
- Polarization effects

Flowing into LISA design !

# Impact

- Success of LISA Pathfinder paving the way to LISA
- Discovering, investigating and resolving many unexpected effects
- Many of the 40+ Ph.D. students are now playing important roles in LISA and other space projects
- Very similar technology is now used for Earth observation and climate research via gravity measurements from space (GRACE-FO, GRACE-C, NGGM)

